

Abstract of the Disclosure

An industrial robot manipulator including a first arm comprising a front arm part and a rear arm part. The front arm part is journaled in the rear arm part such that the front arm part is rotatable about a first axis relative to the rear arm part. Cabling extends along the front arm part and the rear arm part. A supporting device is operative to support the cabling. The supporting device includes a supporting arm arranged in the vicinity of the rear arm part and rotatably supported about a second axis and an auxiliary arm operatively connected to the front arm part. The supporting arm applies a spring pulling force on the cabling in a longitudinal direction of the cabling.